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A Mixture of Viscous Elastic Materials  
with Different Constituent Temperatures

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A Mixture of Viscous Elastic Materials  
with Different Constituent Temperatures

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Abstract. Constitutive equations are discussed for a mixture of any number of materials with elastic and viscous properties in which the constituents may have different temperatures.

1. Introduction

The recent literature on the continuum theory of mixtures contains rather diverse points of view in the primitive concepts and the forms of the basic field equations. The basic equations representing balances of masses, linear momenta, moments of momenta, and energy for each constituent together with equations for the mixture as a whole obtained by summation, as developed by Truesdell [1,2], Truesdell and Toupin [3] and a number of other writers are closely related and are based on similar points of view. On the other hand, the development of the theory by Green and Naghdi [4] and Mills [5] is based on different primitive concepts and consequently some of their resulting equations have different forms from those in [1,3]. However, in a recent paper confined to mixtures with a single temperature, the differences and the relationship between the two approaches have been clarified by Green and Naghdi [6]:

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The basic equations in the two developments are equivalent, although this is not apparent at first sight in the case of some of the equations\* -- the differences lie chiefly in the primitive concepts, the premise under which the two forms of the theory are developed, in addition to the interpretations associated with some of the quantities which occur in the equations. For further detail regarding the relationship between the two forms of the theory, as well as additional references on the subject, we refer the reader to [6].

In the present paper, we are concerned with a mixture of any number of constituents each of which is at a different temperature. Since we now regard the previous paper of Green and Naghdi [7] involving many temperatures as too restrictive, we first reconsider here the forms of the basic equations, as well as the entropy inequality for the mixture as a whole. Although the discussion of the basic equations in sections 3-5 involves some repetition of known results, it is included here in order to have the basic equations in line with our point of view [6] and in terms of variables which we believe provide simple interpretations when discussing constitutive equations.

In section 6, we first briefly outline two procedures for the discussion of constitutive equations and adopt the simpler of the two which is slightly more restrictive than the other. We then consider a mixture of  $v$  constituents (with different temperatures) which are not necessarily gases and which have viscous and elastic properties. In particular, we

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\*In [6], Green and Naghdi have given a different interpretation to the internal energy in the energy equation used by them in [4] and have recast this equation in a slightly different form.

obtain explicit results for the "equilibrium" values of various quantities and also include a discussion of the results when all constituents have the same temperature.

## 2. Notation

We summarize relevant notation for kinematic quantities and density. We consider a mixture of  $\nu$  interacting constituents, each of which is regarded as a continuum; we refer to the  $\alpha^{\text{th}}$  constituent as the continuum  $s_\alpha$  ( $\alpha=1,2,\dots,\nu$ ). We assume that each point within the mixture is occupied simultaneously by all  $\nu$  constituents, which are in motion relative to a fixed system of rectangular Cartesian axes. The position of a typical particle of  $s_\alpha$  at time  $\tau$  is denoted by  $x_i^\alpha(\tau)$ , where

$$x_i^\alpha(\tau) = x_i^\alpha(X_1^\alpha, X_2^\alpha, X_3^\alpha, \tau) \quad (-\infty < \tau \leq t), \quad (2.1)$$

and  $X_i^\alpha$  is a reference position of the particles of  $s_\alpha$ . All Latin indices are tensor indices and take the values 1,2,3, and the usual summation convention is employed. The Greek letter  $\alpha$ , as in (2.1), is reserved for reference to the  $\alpha^{\text{th}}$  constituent of the mixture only. Unless indicated otherwise the summation convention does not apply to Greek indices. We use the notation

$$x_i^\alpha = x_i^\alpha(t) \quad , \quad (2.2)$$

assume that the particles of  $s_\alpha$  ( $\alpha=1,2,\dots,\nu$ ) all occupy the same position at time  $t$  so that

$$x_i^1 = x_i^2 = \dots = x_i^\nu = x_i \quad , \quad (2.3)$$

and we refer to this position at time  $t$  as  $x_i$ .

The velocity vectors at the point  $x_i$  in  $s_\alpha$  at time  $t$  are given by

$$v_i^\alpha = \frac{D^\alpha x_i^\alpha}{Dt} \quad (\alpha = 1, 2, \dots, v) \quad , \quad (2.4)$$

where  $D^\alpha/Dt$  denotes differentiation with respect to  $t$  holding  $X_k^\alpha$  fixed in continuum  $s_\alpha$ . This operator may be written in the form

$$\frac{D^\alpha}{Dt} = \frac{\partial}{\partial t} + v_k^\alpha \frac{\partial}{\partial x_k} \quad . \quad (2.5)$$

Acceleration vectors at time  $t$  are

$$f_i^\alpha = \frac{D^\alpha v_i^\alpha}{Dt} = \frac{\partial v_i^\alpha}{\partial t} + v_k^\alpha \frac{\partial v_i^\alpha}{\partial x_k} \quad (\alpha = 1, 2, \dots, v) \quad , \quad (2.6)$$

the densities of  $s_\alpha$  at time  $t$  are  $\rho_\alpha$  and the rates of deformation and vorticity tensors for  $s_\alpha$  at time  $t$  are given by

$$2d_{ik}^\alpha = v_{i,k}^\alpha + v_{k,i}^\alpha \quad , \quad 2\omega_{ik}^\alpha = v_{i,k}^\alpha - v_{k,i}^\alpha \quad , \quad (2.7)$$

where a comma stands for partial differentiation with respect to  $x_i$ .

We define total density  $\rho$  and mean velocity  $v_i$  by the expressions

$$\rho = \sum_{\alpha=1}^v \rho_\alpha \quad , \quad (2.8)$$

$$\rho v_i = \sum_{\alpha=1}^v \rho_\alpha v_i^\alpha \quad , \quad (2.9)$$

and put

$$u_i^\alpha = v_i^\alpha - v_i, \quad (2.10)$$

so that

$$\sum_{\alpha=1}^v \rho_\alpha u_i^\alpha = 0. \quad (2.11)$$

We also define the operator

$$(\dot{\phantom{x}}) = \frac{D(\phantom{x})}{Dt} = \frac{\partial(\phantom{x})}{\partial t} + v_k \frac{\partial(\phantom{x})}{\partial x_k}, \quad (2.12)$$

and observe that

$$\frac{D}{Dt} = \frac{D}{Dt} + \sum_{\beta=1}^v \frac{\rho_\beta}{\rho} (v_k^\alpha - v_k^\beta) \frac{\partial}{\partial x_k} = \frac{D}{Dt} + u_k^\alpha \frac{\partial}{\partial x_k}. \quad (2.13)$$

### 3. Mass and momentum

Using a fixed surface  $A$  enclosing an arbitrary volume  $V$  the equation of mass balance for  $s_\alpha$  is<sup>+</sup>

$$\frac{\partial}{\partial t} \int_V \rho_\alpha dV + \int_A \rho_\alpha v_k^\alpha n_k dA = \int_V m_\alpha dV, \quad (3.1)$$

where  $m_\alpha$  is density of mass production arising from all the other constituents and  $n_k$  is the unit outward normal to  $A$ . Hence

$$m_\alpha = \frac{\partial \rho_\alpha}{\partial t} + \frac{\partial}{\partial x_k} (\rho_\alpha v_k^\alpha) = \frac{D \rho_\alpha}{Dt} + \rho_\alpha d_{kk}^\alpha, \quad (3.2)$$

and we add the condition

$$\sum_{\alpha=1}^v m_\alpha = 0. \quad (3.3)$$

Next we consider the equation of linear momentum for  $s_\alpha$  in the form

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<sup>+</sup>Alternatively we could use material volume elements of each constituent which coincide at time  $t$ .



$$\begin{aligned}
& \frac{\partial}{\partial t} \int_V \rho_\alpha v_i^\alpha dV + \int_A \rho_\alpha v_i^\alpha v_k^\alpha n_k dA - \int_V m_\alpha \hat{v}_i^\alpha dV \\
& = \int_V (\rho_\alpha F_i^\alpha + p_i^\alpha) dV + \int_A n_k \sigma_{ki}^\alpha dA, \quad (3.4)
\end{aligned}$$

where  $F_i^\alpha$  is external body force applied to  $s_\alpha$  and  $\sigma_{ki}^\alpha$  is the stress tensor<sup>++</sup> associated with the ingredient  $s_\alpha$  so that the total force acting on  $s_\alpha$  across  $A$  per unit area is  $n_k \sigma_{ki}^\alpha$ . The term involving  $\hat{v}_i^\alpha$  is similar to that used by Ingram and Eringen [8] and allows for the fact that momentum is supplied to  $s_\alpha$  not from rest but from all the other constituents of the mixture with some mean velocity  $\hat{v}_i^\alpha$  which will depend on all the velocities of the remaining constituents, but it is not necessary to make any special assumption about this. The vector  $p_i^\alpha$  may now be called a diffusive force acting on  $s_\alpha$ . In addition to (3.4) we impose the condition

$$\sum_{\alpha=1}^N (p_i^\alpha + m_\alpha \hat{v}_i^\alpha) = 0. \quad (3.5)$$

In point form equation (3.4) becomes

$$\sigma_{ki,k}^\alpha + \rho_\alpha (F_i^\alpha - f_i^\alpha) = m_\alpha \dot{v}_i^\alpha - p_i^\alpha - m_\alpha \hat{v}_i^\alpha, \quad (3.6)$$

and we assume that  $p_i^\alpha$  is a vector unaltered by superposed rigid body motions of the whole mixture, apart from orientation. For convenience we say that  $p_i^\alpha$  is objective but other writers give this word a slightly

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<sup>++</sup> Truesdell and Toupin [3] use a different order for the indices on the stress tensor which, in general, is not symmetric.

different meaning. Professor Chadwick has suggested that (3.6) be put in a more convenient form

$$\sigma_{ki,k}^{\alpha} + \rho_{\alpha} (F_i^{\alpha} - f_i^{\alpha}) = \mu_i^{\alpha} + m_{\alpha} u_i^{\alpha} \quad , \quad (3.7)$$

where  $\mu_i^{\alpha}$  is objective and

$$m_{\alpha} v_i^{\alpha} - F_i^{\alpha} - \rho_{\alpha} \wedge v_i^{\alpha} = \mu_i^{\alpha} + m_{\alpha} u_i^{\alpha} \quad , \quad \sum_{\alpha=1}^v \mu_i^{\alpha} = 0 \quad . \quad (3.8)$$

From (3.7) and (3.8) we recover the equations of motion for the mixture as a whole. Thus

$$\sigma_{ki,k} + \sum_{\alpha=1}^v \rho_{\alpha} (F_i^{\alpha} - f_i^{\alpha}) - \sum_{\alpha=1}^v m_{\alpha} v_i^{\alpha} = 0 \quad , \quad (3.9)$$

where

$$\sigma_{ki} = \sum_{\alpha=1}^v \sigma_{ki}^{\alpha} \quad . \quad (3.10)$$

Corresponding to (3.4) we postulate a moment of momentum equation

$$\epsilon_{i,j,k} L_{i,j} = 0 \quad , \quad (3.11)$$

where  $\epsilon_{ijk}$  is the alternating tensor and

$$\begin{aligned}
L_{ij} = & \frac{\partial}{\partial t} \int_V \rho v_i^\alpha x_j dV + \int_A \rho_\alpha v_i^\alpha v_k^\alpha x_j n_k dA - \int_V m_\alpha \hat{v}_i^\alpha x_j dV \\
& - \int_V (\rho_\alpha F_i^\alpha + p_i^\alpha) x_j dV - \int_A n_k \sigma_{ki}^\alpha x_j dA - \int_V \lambda_{ji}^\alpha dV . \quad (3.12)
\end{aligned}$$

In (3.12)  $\lambda_{ji}^\alpha$  is a skew symmetric tensor which may be called the diffusive couple acting on  $s_\alpha$ . With the help of (3.6), equation (3.11) yields

$$\sigma_{[ki]}^\alpha = -\lambda_{ki}^\alpha , \quad (3.13)$$

where  $\sigma_{[ki]}^\alpha$  is the skew symmetric part of  $\sigma_{ki}^\alpha$ . We add the condition

$$\sum_{\alpha=1}^v \lambda_{ki}^\alpha = 0 , \quad (3.14)$$

so that

$$\sigma_{[kil]} = 0 . \quad (3.15)$$

#### 4. Energy balance and entropy production for mixture

Before discussing energy balance equations for each constituent  $s_\alpha$  we obtain the energy equation for the mixture. We assume that

$$\begin{aligned} & \frac{\partial}{\partial t} \int_V \sum_{\alpha=1}^v (\rho_\alpha U_\alpha + \frac{1}{2} \rho_\alpha v_i^\alpha v_i^\alpha) dV \\ & + \int_A \sum_{\alpha=1}^v (\rho_\alpha v_k^\alpha U_\alpha + \frac{1}{2} \rho_\alpha v_k^\alpha v_i^\alpha v_i^\alpha) n_k dA \\ & = \int_V (\rho r + \sum_{\alpha=1}^v \rho_\alpha F_i^\alpha v_i^\alpha) dV + \int_A (\sum_{\alpha=1}^v t_i^\alpha v_i^\alpha - h) dA, \end{aligned} \quad (4.1)$$

where we take

$$t_i^\alpha = n_k \sigma_{ki}^\alpha, \quad h = n_k q_k, \quad q_k = \sum_{\alpha=1}^v q_k^\alpha, \quad \rho r = \sum_{\alpha=1}^v \rho_\alpha r_\alpha, \quad (4.2)$$

$q_k^\alpha$  being the heat flux vector for  $s_\alpha$  and  $q_k$  the heat flux vector for the mixture,  $r_\alpha$  is heat supply per unit mass of  $s_\alpha$ , per unit time, including the heat supply arising from all other constituents, with  $r$  the total heat supply per unit mass of the mixture; the internal heat supplies will be specified by constitutive equations but do not affect the value of  $r$  in (4.2)<sub>4</sub>. Also  $U_\alpha$  is internal energy of  $s_\alpha$  per unit mass, allowing for interaction between  $s_\alpha$  and the other constituents. With the help of (3.7) the point form of (4.1) becomes

$$\begin{aligned} & \rho r - q_{k,k} - \sum_{\alpha=1}^v \left( \rho_\alpha \frac{D U_\alpha}{Dt} + m_\alpha U_\alpha \right) \\ & + \sum_{\alpha=1}^v (\mu_i^\alpha v_i^\alpha + \sigma_{ki}^\alpha v_{i,k}^\alpha + \frac{1}{2} m_\alpha u_i^\alpha u_i^\alpha) = 0. \end{aligned} \quad (4.3)$$

Since

$$\sum_{\alpha=1}^v \left( \rho_{\alpha} \frac{D U_{\alpha}}{Dt} + m_{\alpha} U_{\alpha} \right) = \rho \dot{U} + \Phi, \quad (4.4)$$

where

$$\rho U = \sum_{\alpha=1}^v \rho_{\alpha} U_{\alpha}, \quad \Phi = \sum_{\alpha=1}^v \frac{\partial}{\partial x_k} (\rho_{\alpha} u_k^{\alpha} U_{\alpha}), \quad (4.5)$$

equation (4.3) has the alternative form

$$\rho r - q_{k,k} - \rho \dot{U} - \Phi + \sum_{\alpha=1}^v (\rho_i^{\alpha} v_i^{\alpha} + \sigma_{ki}^{\alpha} v_{i,k}^{\alpha} + \frac{1}{2} m_{\alpha} u_i^{\alpha} u_i^{\alpha}) = 0. \quad (4.6)$$

We adopt an entropy inequality for the mixture which is equivalent to one used by Truesdell [2], namely

$$\begin{aligned} & \frac{\partial}{\partial t} \int_V \sum_{\alpha=1}^v \rho_{\alpha} S_{\alpha} dV + \int_A \sum_{\alpha=1}^v \rho_{\alpha} v_k^{\alpha} S_{\alpha} n_k dA \\ & - \int_V \sum_{\alpha=1}^v \frac{\rho_{\alpha} r_{\alpha}}{T_{\alpha}} dV + \int_A \sum_{\alpha=1}^v \frac{q_k^{\alpha}}{T_{\alpha}} n_k dA \geq 0, \end{aligned} \quad (4.7)$$

where  $T_{\alpha} (> 0)$  is the temperature of the constituent  $s_{\alpha}$  and  $S_{\alpha}$  is its entropy per unit mass. In point form (4.7) becomes

$$\sum_{\alpha=1}^v \left( \rho_{\alpha} \frac{D S_{\alpha}}{Dt} + m_{\alpha} S_{\alpha} \right) - \sum_{\alpha=1}^v \frac{\rho_{\alpha} r_{\alpha}}{T_{\alpha}} + \sum_{\alpha=1}^v \left( \frac{q_k^{\alpha}}{T_{\alpha}} \right)_{,k} \geq 0. \quad (4.8)$$

Except when all the temperatures are equal we cannot develop the consequence of the inequality (4.8) with the help only of (4.3). We need energy equations for each constituent so as to be able to eliminate  $r_\alpha$  from (4.8) and also to provide sufficient equations for the temperatures  $T_\alpha$  ( $\alpha=1,\dots,v$ ). We consider this in the next section.

## 5. Energy balance for each constituent

Recalling quantities defined in previous sections we postulate an energy balance for  $s_\alpha$  in the form

$$\begin{aligned} & \frac{\partial}{\partial t} \int_V \rho_\alpha \left( U_\alpha + \frac{1}{2} v_i^\alpha v_i^\alpha \right) dV + \int_A \rho_\alpha \left( U_\alpha + \frac{1}{2} v_i^\alpha v_i^\alpha \right) v_k^\alpha n_k dA - \int_V \frac{1}{2} m_\alpha \frac{\wedge^\alpha}{v_i} \frac{\wedge^\alpha}{v_i} dV \\ & = \int_V \left\{ \rho_\alpha (r_\alpha + F_i^\alpha v_i^\alpha) + p_i^\alpha v_i^\alpha + \lambda_{ki}^\alpha \omega_{ik}^\alpha \right\} dV \\ & + \int_A (t_i^\alpha v_i^\alpha - n_k^\alpha q_k^\alpha) dA + \int_V \psi_\alpha dV - \int_A n_k^\alpha \bar{q}_k^\alpha dA . \end{aligned} \quad (5.1)$$

The scalar  $\psi_\alpha$  represents a volume contribution to the energy equation arising from interaction, in addition to interactions already considered, and  $n_k^\alpha \bar{q}_k^\alpha$  represents an interaction surface flow of energy with  $\bar{q}_k^\alpha$  an interaction flux vector. However, in point form this vector contributes  $\bar{q}_{k,k}^\alpha$  which can be absorbed into  $\psi_\alpha$ , so without loss of generality we set  $\bar{q}_k^\alpha = 0$ . The constituent  $s_\alpha$  has a mass increase acquired from the other constituents and the rate of change of its kinetic energy just before becoming a part of  $s_\alpha$  is represented by the third group of terms in (5.1). All other quantities in (5.1) have been defined previously and follow naturally from the discussion of sections 3,4.

Equation (5.1) can be reduced to

$$\begin{aligned}
& \int_V \left\{ \rho_\alpha \frac{D U_\alpha}{Dt} + m_\alpha U_\alpha + \rho_\alpha (f_i^\alpha - F_i^\alpha) v_i^\alpha + \frac{1}{2} m_\alpha v_i^\alpha v_i^\alpha - \frac{1}{2} m_\alpha \hat{v}_i^\alpha \hat{v}_i^\alpha \right\} dV \\
& = \int_V (\rho_\alpha r_\alpha + p_i^\alpha v_i^\alpha + \lambda_{ki}^\alpha \omega_{ik}^\alpha + \psi_\alpha) dV + \int_V (t_i^\alpha v_i^\alpha - n_k q_k^\alpha) dA \quad . \quad (5.2)
\end{aligned}$$

if

$$\sum_{\alpha=1}^v (\psi_\alpha + \frac{1}{2} m_\alpha \hat{v}_i^\alpha \hat{v}_i^\alpha + p_i^\alpha v_i^\alpha + \lambda_{ki}^\alpha \omega_{ik}^\alpha) = 0 \quad , \quad (5.3)$$

and if we also use (4.2), then by summation of equations (5.2) we find that

$$\begin{aligned}
& \int_V \sum_{\alpha=1}^v \left\{ \rho_\alpha \frac{D U_\alpha}{Dt} + m_\alpha U_\alpha - \rho_\alpha r_\alpha + \rho_\alpha (f_i^\alpha - F_i^\alpha) v_i^\alpha + \frac{1}{2} m_\alpha v_i^\alpha v_i^\alpha \right\} dV \\
& = \int_A \left( \sum_{\alpha=1}^v t_i^\alpha v_i^\alpha - n_k q_k^\alpha \right) dA \quad . \quad (5.4)
\end{aligned}$$

Equation (5.4) is the same as (4.1) and with the help of (3.7) we recover the point form (4.3).

Using (3.8), as well as (3.13) and (3.3), equation (5.3) reduces to

$$\sum_{\alpha=1}^v (\mu_i^\alpha v_i^\alpha + \sigma_{[ki]}^\alpha \omega_{ik}^\alpha + \frac{1}{2} m_\alpha u_i^\alpha u_i^\alpha - \psi_\alpha) = 0 \quad , \quad (5.5)$$

where

$$\psi_\alpha = \psi_\alpha + \frac{1}{2} m_\alpha (\hat{v}_i^\alpha - v_i^\alpha) (\hat{v}_i^\alpha - v_i^\alpha) \quad . \quad (5.6)$$

Also, with the help of (3.7), (3.13) and (5.6), the point form of (5.2)



becomes

$$\rho_{\alpha} r_{\alpha} - q_{k,k}^{\alpha} - \rho_{\alpha} \frac{D U}{Dt} - m_{\alpha} U_{\alpha} + \sigma_{(ki)}^{\alpha} d_{ik}^{\alpha} + \psi_{\alpha} = 0, \quad (5.7)$$

where  $\sigma_{(ki)}^{\alpha}$  is the symmetric part of  $\sigma_{ki}^{\alpha}$ . The arbitrary functions  $\psi_{\alpha}$  are subject to the condition (5.5). It is desirable to simplify this condition and one way to achieve this is to put<sup>+</sup>

$$\psi_{\alpha} = \mu_i^{\alpha} (v_i^{\alpha} - v_i^v) + \sigma_{[ki]}^{\alpha} (\omega_{ik}^{\alpha} - \omega_{ik}^v) + \frac{1}{2} m_{\alpha} u_i^{\alpha} u_i^{\alpha} + \Theta_{\alpha}, \quad (5.8)$$

so that

$$\sum_{\alpha=1}^v \Theta_{\alpha} = 0, \quad (5.9)$$

and (5.7) becomes

$$\begin{aligned} \rho_{\alpha} r_{\alpha} - q_{k,k}^{\alpha} - \rho_{\alpha} \frac{D U}{Dt} - m_{\alpha} U_{\alpha} + \frac{1}{2} m_{\alpha} u_i^{\alpha} u_i^{\alpha} + \Theta_{\alpha} \\ + \mu_i^{\alpha} (v_i^{\alpha} - v_i^v) + \sigma_{(ki)}^{\alpha} d_{ik}^{\alpha} + \sigma_{[ki]}^{\alpha} (\omega_{ik}^{\alpha} - \omega_{ik}^v) = 0. \end{aligned} \quad (5.10)$$

We observe that for some purposes it is useful to replace the  $v$  equations (5.10) by an equivalent set, namely equation (4.3) and the  $v-1$  equations

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<sup>+</sup>This is not the only possible form for  $\psi_{\alpha}$ . For example, the first terms in (5.8) could be replaced by  $\mu_i^{\alpha} (v_i^{\alpha} - v_i)$ , the difference being absorbed in  $\Theta_{\alpha}$ , but (5.8) is more convenient for our purpose.

$$\begin{aligned}
\rho_{\alpha}^v r_{\alpha}^v - \rho_v^v r_v^v - q_{k,k}^{\alpha} + q_{k,k}^v - \rho_{\alpha}^v \frac{D U_{\alpha}^v}{Dt} + \rho_v^v \frac{D U_v^v}{Dt} - m_{\alpha}^v U_{\alpha}^v + m_v^v U_v^v \\
+ \frac{1}{2} m_{\alpha}^v u_i^{\alpha} u_i^{\alpha} - \frac{1}{2} m_v^v u_i^v u_i^v + \Theta_{\alpha}^v - \Theta_v^v + \mu_i^{\alpha} (v_i^{\alpha} - v_i^v) + \sigma_{(ki)}^{\alpha} d_{ik}^{\alpha} \\
- \sigma_{(ki)}^v d_{ik}^v + \sigma_{[ki]}^{\alpha} (\omega_{ik}^{\alpha} - \omega_{ik}^v) = 0 \quad . \quad (5.11)
\end{aligned}$$

In equation (5.10) the functions  $U_{\alpha}^v$ ,  $\Theta_{\alpha}^v$ ,  $\mu_i^{\alpha}$ ,  $\sigma_{ki}^{\alpha}$ ,  $q_k^{\alpha}$ ,  $m_{\alpha}^v$  are all objective.

If we eliminate  $r_{\alpha}^v$  from (4.8) with the help of (5.10) we obtain the inequality

$$\begin{aligned}
- \sum_{\alpha=1}^v \frac{1}{T_{\alpha}^v} \left\{ \rho_{\alpha}^v \left( \frac{D A_{\alpha}^v}{Dt} + S_{\alpha}^v \frac{D T_{\alpha}^v}{Dt} \right) + m_{\alpha}^v A_{\alpha}^v - \frac{1}{2} m_{\alpha}^v u_i^{\alpha} u_i^{\alpha} - \Theta_{\alpha}^v \right\} \\
+ \sum_{\alpha=1}^v \frac{1}{T_{\alpha}^v} \left\{ \mu_i^{\alpha} (v_i^{\alpha} - v_i^v) + \sigma_{(ki)}^{\alpha} d_{ik}^{\alpha} + \sigma_{[ki]}^{\alpha} (\omega_{ik}^{\alpha} - \omega_{ik}^v) \right\} - \sum_{\alpha=1}^v \frac{q_k^{\alpha} T_{\alpha,k}^v}{T_{\alpha}^v} \geq 0 \quad , \quad (5.12)
\end{aligned}$$

where

$$A_{\alpha}^v = U_{\alpha}^v - T_{\alpha}^v S_{\alpha}^v \quad . \quad (5.13)$$

The inequality (5.12) may be written in an alternative form which is useful for some purposes. Since

$$\begin{aligned}
& \sum_{\alpha=1}^{\nu} \left\{ \frac{\rho_{\alpha}}{T_{\alpha}} \left( \frac{D A_{\alpha}}{Dt} + S_{\alpha} \frac{D T_{\alpha}}{Dt} \right) + \frac{m_{\alpha} A_{\alpha}}{T_{\alpha}} \right\} \\
&= \sum_{\alpha=1}^{\nu} \left\{ \rho_{\alpha} \frac{D}{Dt} \left( \frac{A_{\alpha}}{T_{\alpha}} \right) + \frac{m_{\alpha} A_{\alpha}}{T_{\alpha}} + \frac{\rho_{\alpha}}{T_{\alpha}} \left( S_{\alpha} + \frac{A_{\alpha}}{T_{\alpha}} \right) \frac{D T_{\alpha}}{Dt} \right\} \\
&= \rho \frac{DA}{Dt} + \sum_{\alpha=1}^{\nu} \frac{\partial}{\partial x_k} \left( \frac{\rho_{\alpha} u_k^{\alpha} A_{\alpha}}{T_{\alpha}} \right) + \sum_{\alpha=1}^{\nu} \frac{\rho_{\alpha} S_{\alpha}^*}{T_{\alpha}} \left( \frac{DT}{Dt} + u_k^{\alpha} \frac{\partial T}{\partial x_k} \right), \quad (5.14)
\end{aligned}$$

where

$$S_{\alpha}^* = S_{\alpha} + \frac{A_{\alpha}}{T_{\alpha}}, \quad \rho A = \sum_{\alpha=1}^{\nu} \frac{\rho_{\alpha} A_{\alpha}}{T_{\alpha}}, \quad (5.15)$$

the inequality (5.12) becomes

$$\begin{aligned}
& - \rho \frac{DA}{Dt} - \sum_{\alpha=1}^{\nu} \frac{\rho_{\alpha} S_{\alpha}^*}{T_{\alpha}} \frac{DT}{Dt} + \sum_{\alpha=1}^{\nu} \frac{1}{T_{\alpha}} \left( \frac{1}{2} m_{\alpha} u_i^{\alpha} u_i^{\alpha} + \Theta_{\alpha} \right) \\
& - \sum_{\alpha=1}^{\nu} \frac{\partial}{\partial x_k} \left( \frac{\rho_{\alpha} u_k^{\alpha} A_{\alpha}}{T_{\alpha}} \right) - \sum_{\alpha=1}^{\nu} \frac{q_k^* T_{\alpha,k}}{T_{\alpha}^2} \\
& + \sum_{\alpha=1}^{\nu} \frac{1}{T_{\alpha}} \{ \mu_i^{\alpha} (v_i^{\alpha} - v_i^{\nu}) + \sigma_{(ki)}^{\alpha} d_{ik}^{\alpha} + \sigma_{[ki]}^{\alpha} (w_{ik}^{\alpha} - w_{ik}^{\nu}) \} \geq 0, \quad (5.16)
\end{aligned}$$

where

$$q_k^{\alpha} = q_k^{\alpha} + \rho_{\alpha} T_{\alpha} u_k^{\alpha} S_{\alpha}^*. \quad (5.17)$$

We observe that

$$\sum_{\alpha=1}^{\nu} \frac{\rho_{\alpha} u_k^{\alpha} A_{\alpha}}{T_{\alpha}} = \sum_{\alpha=1}^{\nu} \phi_{\alpha} (v_k^{\alpha} - v_k^{\nu}) = \sum_{\alpha=1}^{\nu} \phi_{\alpha} v_k^{\alpha} , \quad (5.18)$$

$$\phi_{\alpha} = \rho_{\alpha} \left( \frac{A_{\alpha}}{T_{\alpha}} - A \right) , \quad \sum_{\alpha=1}^{\nu} \phi_{\alpha} = 0 .$$

Hence, if we put

$$\mu_i^{\alpha} = T_{\alpha} \frac{\partial \phi}{\partial x_k} + \bar{\mu}_i^{\alpha} \quad (\alpha=1, \dots, \nu-1) , \quad \sigma_{ki}^{\alpha} = T_{\alpha} \phi_{\alpha} \delta_{ki} + \bar{\sigma}_{ki}^{\alpha} \quad (\alpha=1, \dots, \nu), \quad (5.19)$$

the inequality (5.16) reduces to

$$\begin{aligned} & - \rho \frac{DA}{Dt} - \sum_{\alpha=1}^{\nu} \frac{\rho_{\alpha} S_{\alpha}^*}{T_{\alpha}} \frac{DT_{\alpha}}{Dt} + \sum_{\alpha=1}^{\nu} \frac{1}{T_{\alpha}} \left( \frac{1}{2} m_{\alpha} u_i^{\alpha} u_i^{\alpha} + \Theta_{\alpha} \right) \\ & + \sum_{\alpha=1}^{\nu} \frac{1}{T_{\alpha}} \{ \bar{\mu}_i^{\alpha} (v_i^{\alpha} - v_i^{\nu}) + \bar{\sigma}_{(ki)}^{\alpha} d_{ik}^{\alpha} + \bar{\sigma}_{[ki]}^{\alpha} (\omega_{ik}^{\alpha} - \omega_{ik}^{\nu}) \} \\ & - \sum_{\alpha=1}^{\nu} \frac{q_k^{\alpha} T_{\alpha,k}}{T_{\alpha}^2} \geq 0 , \end{aligned} \quad (5.20)$$

and

$$\mu_i^{\nu} = - \sum_{\alpha=1}^{\nu-1} \mu_i^{\alpha} , \quad \sum_{\alpha=1}^{\nu} \bar{\sigma}_{[ki]}^{\alpha} = 0 . \quad (5.21)$$

For later convenience we introduce the notation

$$\theta_{\alpha} = \frac{1}{T_{\alpha}} , \quad \Delta_{\alpha} = \theta_{\alpha} - \theta_{\nu} , \quad V_k^{\alpha} = v_k^{\alpha} - v_k^{\nu} , \quad \Gamma_{ik}^{\alpha} = \omega_{ik}^{\alpha} - \omega_{ik}^{\nu} , \quad (5.22)$$

so that (5.20) becomes

$$- \rho \frac{DA}{Dt} + \sum_{\alpha=1}^v \frac{\rho_{\alpha} S_{\alpha}^*}{\theta_{\alpha}} \frac{D\theta_{\alpha}}{Dt} + \frac{1}{2} \sum_{\alpha=1}^v \theta_{\alpha} m_{\alpha} u_i^{\alpha} u_i^{\alpha} + \sum_{\alpha=1}^{v-1} \Theta_{\alpha} \Delta_{\alpha}$$

$$+ \sum_{\alpha=1}^v (\theta_v + \Delta_{\alpha}) \{ \bar{\mu}_i^{\alpha} v_i^{\alpha} + \bar{\sigma}_{(ki)}^{\alpha} d_{ik}^{\alpha} + \bar{\sigma}_{[ki]}^{\alpha} \Gamma_{ik}^{\alpha} \}$$

$$+ \sum_{\alpha=1}^v q_k^{*\alpha} \theta_{\alpha,k} \cong 0 \quad . \quad (5.23)$$

## Constitutive equations

We assume that mass elements of each constituent are conserved so that

$$m_{\alpha} = 0, \quad (6.1)$$

and that the constituents of the mixture have elastic and viscous properties. We therefore assume that  $A_{\alpha}$ ,  $S_{\alpha}$ ,  $\sigma_{(ki)}^{\alpha}$ ,  $q_k^{\alpha}$  ( $\alpha=1, \dots, v$ ),  $\mu_{ik}^{\alpha}$ ,  $\sigma_{[ki]}^{\alpha}$ ,  $\epsilon_{\alpha}$  ( $\alpha=1, \dots, v-1$ ), are functions of<sup>+</sup>

$$\theta_{\nu}, \Delta_{\gamma}, F_{ij}^{\beta} = \frac{\partial x_i^{\beta}}{\partial x_j^{\beta}}, G_{ijk}^{\beta} = \frac{\partial^2 x_i^{\beta}}{\partial x_j^{\beta} \partial x_k^{\beta}}, \quad (6.2)$$

$$\theta_{\beta,k}, v_k^{\gamma},$$

and

$$v_{i,k}^{\beta}, \quad (6.3)$$

for  $\beta=1, \dots, v$ ,  $\gamma=1, \dots, v-1$ . In view of invariance conditions under superposed rigid body motions of the whole mixture, the velocity gradients must be replaced by

$$d_{ik}^{\beta}, \Gamma_{ik}^{\gamma}. \quad (6.4)$$

<sup>+</sup> These constitutive equations satisfy equipresence which we regard as a mathematical convenience and not a physical principle.

If we use the inequality (5.12) to obtain restrictions on these constitutive assumptions, it can be shown that  $A$  depends only on

$$T_{\beta}^{\alpha}, F_{ij}^{\beta} \quad (6.5)$$

In addition, further restrictions are placed on  $A_{\alpha}$  and other dependent functions, but there is some algebraic complexity in making explicit deductions about the form of  $A_{\alpha}$  from these restrictions.

Inspection of (5.20) suggests an alternative procedure. We assume the  $A_{\alpha}$ ,  $S_{\alpha}^*$  (and hence  $A$ ,  $S$ ,  $\phi_{\alpha}$ ),  $\bar{\sigma}_{(ki)}^{\alpha}$ ,  $q_k^{*\alpha}$  ( $\alpha=1, \dots, v$ ),  $\bar{\mu}_k^{\alpha}$ ,  $\bar{\sigma}_{[ki]}^{\alpha}$ ,  $\Theta_{\alpha}$  ( $\alpha=1, \dots, v-1$ ) are functions of the variables (6.2) and (6.4). From the inequality (5.20) we again find that  $A$  depends only on the variables (6.5). From (5.17), (5.18) and (5.19) we see that  $q_k^{\alpha}$  and  $\sigma_{ki}^{\alpha}$  are functions of the variables (6.2) and (6.4), but that  $\mu_k^{\alpha}$  are functions of

$$\theta_{\beta,kr}, \frac{\partial G_{ijk}^{\beta}}{\partial X_r^{\beta}}, q_{ik,r}^{\beta}, \Gamma_{ik,r}^{\beta},$$

as well as the variables (6.2) and (6.4). If we add the additional restriction that  $\mu_k^{\alpha}$  should depend only on the quantities (6.2) and (6.4), it follows that  $\phi_{\alpha}$  reduce to functions of the variables

$$\theta_v, \Delta_{\beta}, F_{ij}^{\beta}, v_k^{\beta} \quad (6.6)$$

Using (5.18)<sub>2</sub> and the fact that  $A$  is a function of the quantities (6.5), it follows that  $A_{\alpha}$  reduce to functions of the variables (6.6).

Restrictions on the remaining constitutive equations may now be found from (5.12), (5.16), (5.20) or (5.23), and we use (5.23). This procedure appears to be slightly more restrictive than the first and is the one adopted here.

We adopt the notation

$$Y_A = \{\Delta_\alpha, \theta_{\alpha,k}, V_k^\alpha, d_{ik}^\alpha, \Gamma_{ik}^\alpha\} \quad (A=1, \dots, 16v-7) \quad , \quad (6.7)$$

and we put

$$\begin{aligned} \sigma_{ki}^\alpha &= o\sigma_{ki}^\alpha + e\sigma_{ki}^\alpha \quad , \\ \bar{\sigma}_{ki}^\alpha &= o\bar{\sigma}_{ki}^\alpha + e\bar{\sigma}_{ki}^\alpha \quad , \\ \mu_k^\alpha &= o\mu_k^\alpha + e\mu_k^\alpha \quad , \\ \bar{\mu}_k^\alpha &= o\bar{\mu}_k^\alpha + e\bar{\mu}_k^\alpha \quad , \\ q_k^\alpha &= oq_k^\alpha + eq_k^\alpha \quad , \\ q_k^{*\alpha} &= oq_k^{*\alpha} + eq_k^{*\alpha} \quad , \\ \Theta_\alpha &= o\Theta_\alpha + e\Theta_\alpha \quad , \end{aligned} \quad (6.8)$$

where the quantities with a prefix  $o$  are the values of the corresponding quantities on the left hand side of (6.8) when  $Y_A = 0$ . The remaining terms in (6.8) may be regarded as polynomials of degree greater than zero in the functions  $Y_A$  with coefficients which are functions of the remaining variables in (6.2).



With the help of (5.20) we have

$$\rho_{\alpha} S_{\alpha}^{*} = \rho_{\alpha} \frac{\partial A}{\partial \theta_{\alpha}} = - \rho T_{\alpha} \frac{\partial A}{\partial T_{\alpha}}, \quad (6.9)$$

so that

$$\rho_{\alpha} S_{\alpha} = \theta_{\alpha} \sum_{\beta=1}^{\nu} \rho_{\beta} \theta_{\beta} \frac{\partial A_{\beta}}{\partial \theta_{\alpha}} = - T_{\alpha} \sum_{\beta=1}^{\nu} \frac{\rho_{\beta}}{T_{\beta}} \frac{\partial A_{\beta}}{\partial T_{\alpha}}. \quad (6.10)$$

Also, we write

$$A_{\alpha} = A'_{\alpha} + A''_{\alpha}, \quad A = A' + A'', \quad \rho A' = \theta_{\nu} \sum_{\alpha=1}^{\nu} \rho_{\alpha} A'_{\alpha}, \quad (6.11)$$

where  $A'_{\alpha}$  are the values of  $A_{\alpha}$  when  $\Delta_{\beta}$ ,  $V_k^{\beta}$  vanish, and  $A'$  is the value of  $A$  when  $\Delta_{\beta}$  vanishes. For the present we regard  $A''_{\alpha}$  as a polynomial of degree greater than zero in  $\Delta_{\beta}$ ,  $V_k^{\beta}$  and  $A''$  as a polynomial of degree greater than zero in  $\Delta_{\beta}$  with coefficients which are functions of  $\theta_{\nu}$ ,  $F_{ij}^{\beta}$ . The result (6.11)<sub>3</sub> follows from (5.15)<sub>2</sub>. Again, using (5.23), we have

$$\bar{o}_{\sigma ki}^{\alpha} = \frac{\rho}{\theta_{\nu}} \frac{\partial A'}{\partial F_{ij}^{\alpha}} F_{kj}^{\alpha}, \quad (6.12)$$

$$\bar{o}_{\mu k}^{\alpha} = \frac{1}{\theta_{\nu}} \sum_{\beta=1}^{\nu} \left( \rho_{\alpha} \frac{\partial A'}{\partial F_{ij}^{\beta}} G_{ijr}^{\beta} \frac{\partial X_r^{\beta}}{\partial x_k^{\beta}} - \rho_{\beta} \frac{\partial A'}{\partial F_{ij}^{\alpha}} G_{ijr}^{\alpha} \frac{\partial X_r^{\alpha}}{\partial x_k^{\alpha}} \right), \quad (6.13)$$

for  $\alpha=1, \dots, \nu$  provided

$$\sum_{\alpha=1}^{\nu} \left( \frac{\partial A'}{\partial F_{ij}^{\alpha}} F_{kj}^{\alpha} - \frac{\partial A'}{\partial F_{kj}^{\alpha}} F_{ij}^{\alpha} \right) = 0 \quad (6.14)$$

Also

$$o_{\alpha}^{\alpha} = 0, \quad o_{q_k}^{*\alpha} = 0, \quad o_{q_k}^{\alpha} = 0 \quad (6.15)$$

In addition there is a residual inequality which we omit. From (5.18), (5.19), (6.12) and (6.13) we then have

$$o_{\sigma_{ki}}^{\alpha} = \sum_{\beta=1}^{\nu} \rho_{\beta} \frac{\partial A'}{\partial F_{ij}^{\alpha}} F_{kj}^{\beta}, \quad (6.16)$$

$$o_{\mu_k}^{\alpha} = \sum_{\beta=1}^{\nu} \left( \rho_{\alpha} \frac{\partial A'}{\partial F_{ij}^{\alpha}} G_{ijr}^{\beta} \frac{\partial x_r^{\beta}}{\partial x_k^{\alpha}} - \rho_{\beta} \frac{\partial A'}{\partial F_{ij}^{\beta}} G_{ijr}^{\alpha} \frac{\partial x_r^{\alpha}}{\partial x_k^{\beta}} \right), \quad (6.17)$$

in agreement with previous results [9].

The above constitutive equations are subject to the usual invariance conditions under superposed rigid body motions of the whole mixture.

For example,  $A_{\alpha}$ ,  $A$  reduce to the new forms

$$A_{\alpha} = A_{\alpha}(\theta_{\nu}, \Delta_{\nu}, \frac{\partial x_r^{\alpha}}{\partial x_i^{\alpha}} \frac{\partial x_r^{\beta}}{\partial x_j^{\beta}}, \frac{\partial x_r^{\alpha}}{\partial x_i^{\alpha}} v_r^{\beta}) \quad (6.18)$$

$$A = A(\theta_{\nu}, \Delta_{\nu}, \frac{\partial x_r^{\alpha}}{\partial x_i^{\alpha}} \frac{\partial x_r^{\beta}}{\partial x_j^{\beta}}) \quad (6.19)$$

for  $\alpha, \beta = 1, \dots, \nu$ ,  $\nu = 1, \dots, \nu-1$ . In view of (6.19) we may verify that the condition (6.14) is satisfied.

In obtaining the above constitutive equations, we have adopted the second procedure described earlier in this section [after (6.5)]. We

note that if we had used the first method, we would still recover the results (6.9), (6.12), (6.13), (6.16) and (6.17) with  $A'_\alpha$  being the "equilibrium" values of  $A_\alpha$ , i.e., the values of  $A_\alpha$  when  $Y_A$  vanish.

The special case of the formulae (6.10) when all the temperatures are equal is of some interest. In order to see what happens to (6.10) we write

$$\theta_v = \Delta \quad , \quad \theta_\alpha - \theta_v = \Delta_\alpha \quad (\alpha = 1, \dots, v-1) \quad , \quad (6.20)$$

then

$$\frac{\partial}{\partial \theta_\alpha} = \frac{\partial}{\partial \Delta_\alpha} \quad (\alpha \neq v) \quad , \quad (6.21)$$

$$\frac{\partial}{\partial \theta_v} = \frac{\partial}{\partial \Delta} - \sum_{\alpha=1}^{v-1} \frac{\partial}{\partial \Delta_\alpha} \quad ,$$

and

$$\sum_{\alpha=1}^v \theta_\alpha \frac{\partial}{\partial \theta_\alpha} = \Delta \frac{\partial}{\partial \Delta} + \sum_{\alpha=1}^{v-1} \Delta_\alpha \frac{\partial}{\partial \Delta_\alpha} \quad . \quad (6.22)$$

The functions  $A_\beta$  may be expressed in the form

$$A_\beta = A_\beta^*(F_{ij}^\alpha, V_k^\alpha, \Delta, \Delta_v) \quad . \quad (6.23)$$

When

$$\Delta_v = 0 \quad (v=1, \dots, v-1) \quad , \quad \Delta = 1/T \quad , \quad (6.24)$$

where  $T$  is the common temperature of the constituents, we assume that

$$A_\beta \rightarrow A_\beta^*(F_{ij}^\alpha, V_k^\alpha, T) \quad , \quad (6.25)$$

$$\frac{\partial A_{\beta}}{\partial \Delta} \rightarrow \frac{\partial A_{\beta}^*}{\partial \Delta} = - \frac{1}{\Delta^2} \frac{\partial A_{\beta}^*}{\partial T} \quad (6.26)$$

It will not, in general, be possible to evaluate  $\partial A_{\beta}/\partial \Delta_{\gamma}$  as  $\Delta_{\gamma} \rightarrow 0$  in terms of the function  $A_{\beta}^*$  and we assume that these derivatives are replaced by arbitrary finite scalar functions<sup>†</sup>. From (6.10) and (6.21) we see that under the condition (6.24),

$$\sum_{\alpha=1}^{\nu} \rho_{\alpha} S_{\alpha} = \sum_{\beta=1}^{\nu} \Delta^2 \rho_{\beta} \frac{\partial A_{\beta}^*}{\partial \Delta} = - \sum_{\beta=1}^{\nu} \rho_{\beta} \frac{\partial A_{\beta}^*}{\partial T} \quad (6.27)$$

or, defining

$$\rho S = \sum_{\alpha=1}^{\nu} \rho_{\alpha} S_{\alpha} \quad , \quad \rho A^* = \sum_{\beta=1}^{\nu} \rho_{\beta} A_{\beta}^* \quad (6.28)$$

then

$$S = - \frac{\partial A^*}{\partial T} \quad (6.29)$$

as given previously [6,8]. Also  $S_{\alpha} - S_{\nu}$  become arbitrary functions of  $F_{ij}^{\beta}$ ,  $V_k^{\beta}$ ,  $T$  not expressible in terms of  $A_{\beta}^*$ , which again agrees with a previous result [9]. We recall that the energy equations, which provide  $\nu$  differential equations for the  $\nu$  temperatures  $T_{\alpha}$ , may be taken to be (4.3) and the  $\nu-1$  equations (5.11), and we observe that volume supplies of heat may be taken to be given by the  $\nu$  independent quantities

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<sup>†</sup>This is analagous to the procedure used in the passage from a compressible to an incompressible elastic material.

$$\rho r = \sum_{\alpha=1}^v \rho_{\alpha} r_{\alpha} , \quad \rho_{\beta} r_{\beta} = \rho_v r_v \quad (\beta = 1, \dots, v-1) \quad (6.30)$$

When temperatures reduce to a single temperature we have one equation (4.3) for this. The remaining equations (5.11) can then, in general, only be satisfied by appropriate choices for the heat supplies

$\rho_{\beta} r_{\beta} = \rho_v r_v$ . This is similar to the situation in which we can, in general, only maintain isothermal conditions with  $T$  constant by an appropriate choice of  $r$ .

Special cases of the results (6.16) and (6.17) may be obtained without difficulty. For example, if constitutive equations depend on the deformation gradients  $F_{ij}^{\beta}$  only through the densities  $\rho_{\beta}$ , then

$$\sigma_{ki}^{\alpha} = - \delta_{ki} \sum_{\beta=1}^v \rho_{\alpha} \rho_{\beta} \frac{\partial A'_{\beta}}{\partial \rho_{\alpha}} , \quad (6.31)$$

$$\sigma_{k}^{\alpha} = \sum_{\beta=1}^v \left( \rho_{\alpha} \frac{\partial A'_{\alpha}}{\partial \rho_{\beta}} \frac{\partial \rho_{\beta}}{\partial x_k} - \rho_{\beta} \frac{\partial A'_{\beta}}{\partial \rho_{\alpha}} \frac{\partial \rho_{\alpha}}{\partial x_k} \right) , \quad (6.32)$$

as found previously [6]. These results are appropriate for a mixture of viscous fluids.

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